

Three phase AC motor soft starter



Benefits

- Easy to use. RSGT is equipped with a self-learning algorithm that automatically adjusts the start parameters to optimise the motor starts and stops.
- Fast installation and set-up. Only 3 settings are required (FLC, ramp-up and ramp-down).
- Compact dimensions. 12 25 Arms in 45mm wide housing.
- Integrated protection. Diagnostic functions provide additional protection. RSGT is also equipped with an overload protection (Class 10).
- Three phase controlled.
- Torque control during ramp-down. Smoother deceleration of the load.
- Guided model selection. Easy to use selection tool to select the appropriate soft starter model depending on the application type.

Description

RSGT is an extremely compact and easy to use 3-phase soft starter for AC induction motors rated up to 25 Arms.

The starting parameters can be easily set-up through 3 selector switches.

The integrated motor overload protection (Class 10) results in a higher installation flexibility.

Applications

RSGT soft starters are the ideal solution for 3-phase fixed speed AC induction motor applications where there is the need to reduce the starting current and/or minimise stresses on the motor during start and stop. The RSGT offers a number of integrated diagnostic functions that can replace additional components inside the electrical panel.

Typical applications include: compressors, pumps and fans.



Main functions

- Soft starting and soft stopping of AC motors.
- Integrated electronic overload protection (Class 10).
- · Wrong phase sequence detection.
- Toque control during ramp-down.
- Top of ramp and alarm relay indication.



References

Order code

RSGT V1 0

Enter the code entering the corresponding option instead of lacksquare

Code	Option	Description	Notes
R	-	-	
S		Soft starter	
G		General purpose	
Т		Three phase control	
	40	220 – 400 VAC +10% -15% operational voltage (Ue)	
	60	220 – 600 VAC +10% -15% operational voltage (Ue)	
	12	12 Arms	Pated operational current
	16	16 Arms	Rated operational current @ 40 °C
	25	25 Arms	@ 1 0 0
	E0	110 - 400 VAC +10% - 15% control voltage (Uc)	
		Supply voltage: internally supplied	RSGT40 models only
	F0	24 VAC/DC +10% - 10% control voltage (Uc)	The second string
		Supply voltage: internally supplied	
_	FF	24 VAC/DC +10% - 10% control/supply voltage	
		Supply voltage: externally supplied	RSGT60 models only
	GG	100 - 240 VAC +10% - 15% control/supply voltage Supply voltage: externally supplied	
V		ouppily voitage, externally supplied	
<u> </u>		Mith into metal mater availand metals (Class 10)	
1		With integrated motor overload protection (Class 10)	
0		No PTC	

Selection guide

	Operational vo	Itage: 400 VAC	Operational voltage: 600 VAC		
Rated operational current (le)	Control voltage 110 - 400 VAC	Control voltage 24 VAC / DC	Control/supply voltage 100 - 240 VAC	Control/supply voltage 24 VAC / DC	
12 Arms	RSGT4012E0V10	RSGT4012F0V10	RSGT6012GGV10	RSGT6012FFV10	
16 Arms	RSGT4016E0V10	RSGT4016F0V10	RSGT6016GGV10	RSGT6016FFV10	
25 Arms	RSGT4025E0V10	RSGT4025F0V10	RSGT6025GGV10	RSGT6025FFV10	



Further reading

Information	Where to find it	QR
RSGT 45mm instruction manual	http://cga.pub/?6ca01b	
RSGT troubleshooting guide	http://cga.pub/?11a31f	
RSGT 45mm Monitor software	http://cga.pub/?afe4f5	
CAD drawings (RSGT 45mm)	http://cga.pub/?bf3bed	

Selection guide and typical application settings

Category	Туре	Trip Class	Ramp-up setting [s]	Ramp-down setting [s]
	Scroll compressor	5	1	0
0	Screw compressor	5	2 to 5	0
Compressors	Piston compressor	5	2	0
	Centrifugal compressor	10	10	0
	Hydraulic pump	5	2	0
Dumma	Centrifugal pump (start time <10sec)	5	5 to 10	10
Pumps	Centrifugal pump (start time >10sec)	10	10 to 20	15
	Piston pump	10	5 to 10	0
	Centrifugal fan (<0.5m diameter)	10	5 to 10	0
Fans	Centrifugal fan (>0.5m diameter)	20	15 to 20	0
	Vacuum blowers	10	5 to 10	0
Foodoro	Screw feeder	10	2 to 10	0
Feeders	Auger	10	5 to 10	0
	Agitators	10	5 to 15	0
	Mixers	10	5 to 10	0
	Saws (<0.5 m diameter)	10	5 to 10	5
Rotating machinery	Saws (>0.5 m diameter)	20	15 to 20	10
	Grinder	20	15 to 20	0
	Crusher	30	20	0
	Conveyors	10	5 to 10	5

Note: when using the RSGT on high inertia loads (Trip Class 20, 30) ensure that enough time is left between starts to allow the RSGT to cool down.

For Trip Class 20 and Class 30 applications we recommend the use of an external overload protection due to the higher FLC setting that is required on RSGT. The FLC setting for Class 20 and Class 30 applications needs to be set to a higher value with respect to the motor FLC in order not to trip the electronic motor overload protection available on the RSGT soft starters.



Motor FLC [A]	HP Rating @ 230 V	Power kW @ 400 V	Trip class 5	Trip class 10	Trip class 20	Trip Class 30
1.8	0.4	0.75	RSGT4012	RSGT4012	RSGT4012	RSGT4012
2.6	0.6	1.1	RSGT4012	RSGT4012	RSGT4012	RSGT4012
3.4	0.75	1.5	RSGT4012	RSGT4012	RSGT4012	RSGT4012
5	1.0	2.2	RSGT4012	RSGT4012	RSGT4012	RSGT4012
6	1.5	3.0	RSGT4012	RSGT4012	RSGT4012	RSGT4012
9	2.0	3.7	RSGT4012	RSGT4012	RSGT4016	RSGT4025
12	3.0	5.5	RSGT4012	RSGT4012	RSGT4025	RSGT4025
16	5.0	7.5	RSGT4016	RSGT4016	- *	- *
22	7.5	11.0	RSGT4025	RSGT4025	- *	- *

- * Contact Carlo Gavazzi representative for further information.
- Option "E0": 110 400 VAC or option "F0": 24 VAC/DC.

Motor FLC [A]	HP rating @ 480V	HP Rating @ 600V	Trip class 5	Trip class 10	Trip class 20	Trip class 30
1.6	0.75	1	RSGT6012	RSGT6012	RSGT6012	RSGT6012
2.4	1	1.5	RSGT6012	RSGT6012	RSGT6012	RSGT6012
3	1.5	2	RSGT6012	RSGT6012	RSGT6012	RSGT6012
3.9	2	3	RSGT6012	RSGT6012	RSGT6012	RSGT6012
5	3	4	RSGT6012	RSGT6012	RSGT6012	RSGT6012
6	3	5	RSGT6012	RSGT6012	RSGT6012	RSGT6012
9	5	7.5	RSGT6012	RSGT6012	RSGT6012	RSGT6012
11	7.5	10	RSGT6012	RSGT6012	RSGT6016	RSGT6025
16	10	15	RSGT6016	RSGT6016	- *	- *
22	15	20	RSGT6025	RSGT6025	- *	- *

- * Contact Carlo Gavazzi representative for further information.
- Option "GG": 100 240 VAC or option "FF": 24 VAC/DC.

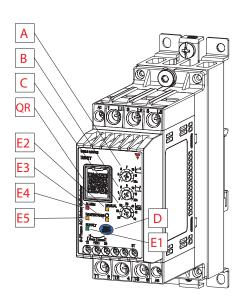
Caution: the actual motor Amps may be higher or lower than the average values listed above. We suggest to use the actual motor current as listed on the motor nameplate. Use this table as a guide only.

CARLO GAVAZZI compatible components

Purpose	Component name/code	Notes
Manual motor starters	GMS-32 🗖 - 🗖	H: high breaking capacity
PC interface cable (Isolated USB to TTL cable)	RS-USB	For RSGT12 to RSGT25



Structure



Element	Component	Function
Α	Ramp-up time selector	Sets the desired motor starting time.
В	Ramp-down time selector	Sets the desired motor stopping time.
С	FLC selector	Sets the motor full load current (FLC). The FLC setting is used by the RSGT for the overload protection and for the maximum current allowed during motor start.
D	Test/Reset	Simulate overload alarm (press for 1 sec when RSGT is in Idle state) Set alarm recovery mode (press for 5 sec when RSGT is in Idle state) Reset alarms (press for <1 sec when RSGT is in alarm mode and alarm mode is Manual) Enable/disable phase sequence protection (press for 10 sec when RSGT is in Idle state) Enable/disable dry run function (press for 3 sec when RSGT is in Idle state) Enable/disable overload function (press for 8 sec when RSGT is in Idle state) Note: While the Test/Reset button is pressed the LED E5 will start flashing with a frequency of 1 Hz in order to help the user count the seconds elapsed.
E1	LED indicators	Supply. Indicates that the RSGT supply is ON.
E2	LED indicators	Manual. Indicates the alarm reset mode. Manual reset mode - LED ON, Auto reset mode - LED OFF (Factory default setting: Auto, LED OFF)
E3	LED indicators	Phase sequence. Indicates if the wrong phase sequence protection is enabled (LED OFF) or disabled (LED ON). (Factory default setting: Enabled, LED OFF)
E4	LED indicators	Alarm. Indicates that the RSGT is in alarm. The number of flashes indicates the alarm type.
E5	LED indicators	Ramping/bypass. Indicates whether RSGT is in ramping (flashing) or bypass (fully ON). Note: Ramping - not HP: 2 Hz flashing. Ramping - HP: 10 Hz flashing.
QR	QR code	Scan to link to troubleshooting guide.



Mode of operation

The RSGT series of soft starters works on two distinct self-learning algorithms depending on the ramp-up time settings.

Ramp-up	Mode of operation
1 or 2 seconds	 When the ramp-up selector is in position 1 or 2, the RSGT will follow a self-learning current limit algorithm. As soon as A1-A2 (or ST for RSGT60 models) control voltage signal is applied, the RSGT will start to ramp-up the motor. At the very first start the current limit will be 4 x FLC setting. In the subsequent starts, the RSGT will automatically adjust the current limit setting to maintain the motor start time as close as possible to the ramp-up time setting.
≥ 5 seconds	 When the ramp-up selector is in position 5 or above, the RSGT will follow a self-learning current ramp algorithm. The RSGT will start with a set of default parameters for starting torque. Depending on the ramp-up time setting, the RSGT will apply a current ramp algorithm to start the motor as close as possible to the set ramp-up time. During the motor start, the current will be limited to a maximum of 3.5 x FLC setting. In the subsequent starts, the RSGT will continue to adjust the starting parameters of initial torque and current ramp to ensure that the motor is started as close as possible to the set ramp-up time.

Ramp-down	Mode of operation
1 to 20 seconds	 During ramp-down, the RSGT works on a torque control algorithm for smoother stopping of the motor. As soon as the control voltage signal A1-A2 (or ST for RSGT 60 models) is removed, the RSGT will slow down the motor gradually according to the ramp-down setting. The power semiconductors will be switched OFF as soon as the time (as per ramp-down setting) has elapsed unless there is a risk of exceeding the maximum temperature on the semiconductors. In such a case the RSGT will leave the motor to coast to stop.
0 seconds	• If the ramp-down selector is set to 0, the RSGT will leave the motor to coast to stop (no ramp-down).



Features

General

	RSGT 45 mm
Material	PA66
Assembly	DIN or panel
Protection grade	IP20
Weight	0.5 to 0.75 Kg
Overvoltage category	Cat. III

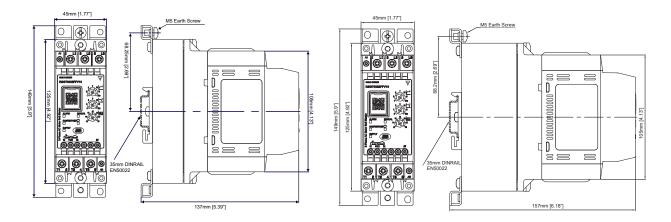


Fig. 1 RSGT..12..to RSGT..16.. | | Fig. 2 RSGT..25..

Settings

	RSGT 45 mm
Ramp-up time	1 - 20 s
Ramp-down time	0 - 20 s
Initial torque	Automatically determined by RSGT
	RSGT 12: 2 - 12 A
FLC range settings	RSGT 16: 6 - 16 A
	RSGT 25: 12 - 25 A



Power Supply

	RSGT40	RSGT60	
Operational voltage range	187 - 440 VACrms	187 - 660 VACrms	
Supply current at Idle	< 30 n	nArms	
Blocking voltage	1200 Vp	1600 Vp	
Rated AC frequency	50/60 Hz (+/- 10%)		
Rated insulation voltage	600 VAC 690 VAC		
Dielectric withstand voltage:			
Supply to input	2.5 kVrms		
Supply to heatsink	2.5 kVrms		
Integrated varistor	Yes		

Environmental

Working temperature	-20°C to +60°C (-4°F to +140°F). Note: for temperatures > 40°C derating applies.
Storage temperature	-40°C to +80°C (-40°F to +176°F).
Relative humidity	< 95% non-condensing @ 40°C.
Pollution degree	2
Installation category	
Installation altitude	1000 m
Vibration	Acc. to IEC/EN 60068-2-6
Frequency 1	2 [+3/-0] Hz to 25 Hz displacement +/- 1.6 mm
Frequency 2	10 Hz to 55 Hz @ 2g (19.96m/s²) @ constant displacement



Compatibility and conformity

Standard compliance	IEC/EN 60947-4-2
Approvals	C € ER[



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Electromagnetic compatibility (E	Electromagnetic compatibility (EMC) - immunity		
Electrostatic discharge (ESD)	EN/IEC 61000-4-2		
	8 kV air discharge, 4 kV contact.		
	EN/IEC 61000-4-3		
Padiated radio fraguency	10 V/m, from 80 MHz to 1 GHz (PC1)		
Radiated radio frequency	10 V/m, from 1.4 to 2 GHz (PC1)		
	3 V/m, from 2 to 2.7 GHz (PC1)		
	EN/IEC 61000-4-4		
Electrical fact transient (buret)	AC input: 2 kV, 5 kHz & 100 kHz (PC1)		
Electrical fast transient (burst)	DC input: 1 kV, 5 kHz (PC2)		
	Signal and control: 2 kV, 5 kHz & 100 kHz (PC1)		
Canduated radio fraguency	EN/IEC 61000-4-6		
Conducted radio frequency	10 V/m, from 0.15 to 80 MHz		
	EN/IEC 61000-4-5		
	Output, line to line: 1 kV (PC2)		
	Output, line to earth: 2 kV (PC1)		
Electrical curso	AC input, line to line: 1 kV (PC1)		
Electrical surge	AC input, line to earth: 2 kV (PC1)		
	DC input, line to line: 1 kV (PC2)		
	DC input, line to earth: 2 kV (PC2)		
	Signal and control, line to earth: 2 kV (PC1)		
	EN/IEC 61000-4-11		
Voltage dips	0% for 10 ms and 20 ms (PC2)		
	40% for 100, 200, 1000 ms (PC2)		
	70% for 500 ms (PC2)		
	80% for 5000 ms (PC2)		
	0% for 5000 ms (PC2)		

Electromagnetic compatibility (EMC) - emissions		
Radio interference field emis-	EN/IEC 55011	
sion (radiated)	Class A (Industrial): from 30 to 1000 MHz	
Radio interference voltage	EN/IEC 55011	
emissions (conducted)	Class A (Industrial): from 0.15 to 30 MHz	



Inputs

	RSGT40E0V	RSGT40F0V	RSGT60FFV	RSGT60GGV
Control voltage (Uc)	A1 - A2: 110 - 400 VAC +10%, -15%	A1 - A2: 24 VAC/VDC +10%, -10%	ST: 24 VAC/VDC +10%, -15%	ST: 100 - 240 VAC +10%, -15%
Control voltage range (Uc)	93.5 - 440 VAC	21.6 - 26.4 VAC/DC	21.6 - 26.4 VAC/DC	85 - 264 VAC
Maximum pick-up voltage	80 VAC	20.4 VAC/DC	20.4 VAC/DC	80 VAC
Minimum drop out voltage	20 VAC	5 VAC/DC	5 VAC/DC	20 VAC
Supply voltage range (Us)	-	-	A1 - A2: 24 VAC/DC +10%, -10%	A1 - A2: 100 - 240 VAC +10%, -15%
Rated AC frequency	45 - 66 Hz 45 - 66 Hz (applies to 24 VAC supply) 45 - 66 Hz		45 - 66 Hz	
Rated insulation voltage (Ui)	500 VAC			
Dielectric strength: Dielectric withstand voltage Rated impulse withstand voltage	2 kVrms 4 kVrms			
Control input current	0.55 - 1.3 mArms	0.4 - 1 mArms	0.5 - 1.5 mArms	0.4 - 3 mArms
Input to output response time (Mains supply already present)	200 ms			
Input to output response time (Mains supply applied with control)	2 sec 3 sec		sec	
Integrated varistor	Yes			

Note 1: for the Canadian application, the control terminals A1, A2 (or A1, A2, ST for RSGT60 versions) of the RSGT devices shall be supplied by a secondary circuit where power is limited by a transformer, rectifier, voltage divider, or similar device that derives power from a primary circuit, and where the short-circuit limit between conductors of the secondary circuit or between conductors and ground is 1500VA or less. The short-circuit volt ampere limit is the product of the open circuit voltage and the short circuit ampere.

Note 2: RSGT60GG soft starters require a separate 100 - 240V, 50/60 Hz single phase control source, while RSGT60FF requires 21.6 - 26.4 VAC/DC. Output connections (L1, L2, L3, T1, T2, T3) are not galvanically isolated from the external supply connections (A1, A2, ST).



Outputs

	RSGT12	RSGT16	RSGT25
Overload cycle @ 40°C surrounding tempera- ture (acc. to EN/IEC 60947-4-2)	AC53b: 3 - 12 : 288		
Maximum number of starts/hr @ rated overload cycle @ 40°C surrounding temperature		12	
Rated operational current @ 40°C	12 Arms	16 Arms	25 Arms
Rated operational current @ 50°C	12 Arms	15 Arms	23 Arms
Rated operational current @ 60°C	12 Arms	13 Arms	21 Arms
Minimum load current		1 Arms	

Note: the overload cycle describes the switching capability of the soft starter at a surrounding temperature of 40°C as described in EN/IEC 60947-4-2. An overload cycle AC53b:3-12:288 means that the soft starter can handle a starting current of 3x le for 12 seconds followed by an OFF time of 288 seconds amounting to a total cycle time of 300s resulting in 12 starts/hr.

Auxiliary relays

	RSGT 45mm
Number of output relays	2
Function of relays	Alarm, bypassed (top of ramp).
Rated operational voltage	250 VAC/30 VDC
Rated insulation voltage	250 VAC
Dielectric withstand voltage	2.5 kV
Overvoltage category	II
Type of control circuit	Electromechanical relay
Number of contacts	Alarm and bypassed: 1
Type of contacts	Alarm: normally closed (NC)
Type of contacts	Bypassed: normally open (NO)
Type of current	AC / DC
Rated operational current	3 Arms @ 250 VAC, 3 Arms @ 30 VDC



Performance



Current / power ratings: kW and HP @ 40°C

Model	IEC Rated Current	220 - 240 VAC	380 - 415 VAC	440 - 480 VAC	550 - 600 VAC
RSGT12	12 Arms	3 kW / 3 HP	5.5 kW / 5 HP	5.5 kW / 7.5 HP	9 kW / 10 HP
RSGT16	16 Arms	4 kW / 5 HP	7.5 kW / 7.5 HP	9 kW / 10 HP	11 kW / 15 HP
RSGT25	25 Arms	5.5 kW / 7.5 HP	11 kW / 10 HP	11 kW / 15 HP	20 kW / 20 HP

Ratings:

kW rating according to: IEC/EN 60947-4-2



Starts per hour

The table below indicates the maximum number of starts/hr that can be done by the different RSGT models at different operating currents with a surrounding temperature of 40°C.

Model	Operational current			
	6 Arms	12 Arms	16 Arms	25 Arms
RSGT12V10	26	12	-	-
RSGT16V10	37	17	12	-
RSGT25V10	64	29	21	12



Connection Diagrams

Terminal markings



Fig. 3 RSGT 45mm

Morking	RSGT 45 mm		
Marking	RSGT40	RSGT60	
1 L1, 3 L2, 5 L3	Line con	nections	
2 T1, 4 T2, 6 T3	Load cor	nnections	
A1, A2	Control voltage	Supply voltage	
ST	-	Control voltage	
11, 12	Alarm indication (normally closed, NC)		
21, 24	Top of ramp indication (normally open, NO)		
Note:	For the 24 VDC (RSGT40F0, RSGT60FF) models, connect A1 to the positive (+) and A2 to the negative (-) terminal.		



Wiring diagrams

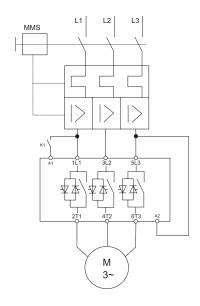


Fig. 4 RSGT40E0...

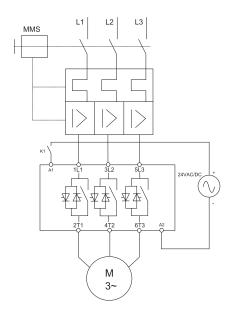


Fig. 5 RSGT40F0...

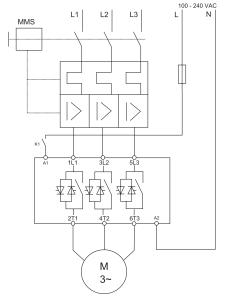


Fig. 6 RSGT40E0...

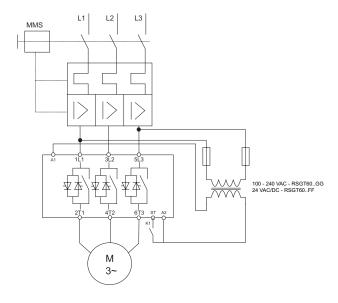


Fig. 7 RSGT60. GG models: Apply 100 - 240VAC, FF models: Apply 24VAC/DC

*Note: It is recommended that the power factor correction capacitors be switched out of the circuit during the ramp-up phase. When the RSGT is in the bypass state (bypass relays closed), the capacitor may be switched back into the circuit. Capacitors may affect the proper operation of the silicon controlled rectifiers (SCRs) if kept in the circuit during the start ramp.



Connection specifications

Line conductors 1 L1, 3 L2, 5 L3, 2 T1, 4 T2, 6 T3 Acc. to EN60947-1		
	RSGT12 to RSGT25	
Flexible	2.5 - 10 mm ²	
1 TOXIDIO	2.5 - 2 x 4 mm ²	
Rigid (solid or stranded)	2.5 10 mm ²	
Flexible with end sleeve	2.5 10 mm²	
(ferrule)	2.5 10 111111	
UL/cUL rated data		
Rigid (stranded)	AWG 614	
Rigid (solid)	AWG 1014	
Rigid (solid or stranded)	AWG2 x 102 x 14	
Terminal screws	M4	
Maximum tightening torque	2.5 Nm (22 lb.in) with pozidriv bit 2	
Stripping length	8.0 mm	

Secondary conductors A1, A2 Acc. to EN60998		
	RSGT12 to RSGT25	
Flexible	0.5 1.5 mm²	
Rigid (solid or stranded)	0.5 2.5 mm²	
Flexible with end sleeve	0.5 1.5 mm²	
(ferrule)	0.5 1.5 111111	
UL/cUL rated data		
Rigid (solid or stranded)	AWG 1018	
Terminal screws	M3	
Maximum tightening torque	0.6 Nm (5.3 lb.in) with pozidriv bit 0	
Stripping length	6.0 mm	

Auxiliary conductors 11, 12, 21, 24, ST		
	RSGT12 to RSGT25	
Rigid (solid or stranded)	0.05 2.5 mm²	
Flexible with end sleeve	$0.05 \dots 1.5 \ mm^2$	
(ferrule)	0.05 1.5 11111	
UL/cUL rated data		
11, 12, 21, 24, ST	AWG 30 12	
Rigid (solid or stranded)	AWG 24 12	
Terminal screws		
11, 12, 21, 24, ST	M3	
Maximum tightening torque		
11, 12, 21, 24, ST	0.45 Nm (4.0 lb.in) pozidriv bit 0	
Stripping length	6.0 mm	

Use 75°C Copper (Cu) conductors



Troubleshooting



LED status indications

State	Supply (green LED)	Ramp/Bypass (yellow LED)	Alarm (red LED)	Manual (yellow LED)
Idle	ON	OFF	OFF	OFF/ON
Ramping	ON	Flashing	OFF	OFF/ON
Bypass	ON	ON	OFF	OFF/ON
Alarm (Auto-recovery)	ON	OFF	Flashing	OFF
Alarm (Manual recovery)	ON	OFF	Flashing	ON
Internal fault	ON	OFF	ON	OFF/ON
Idle (Start to start or stop to start time not elapsed)	Flashing	OFF	OFF	OFF/ON

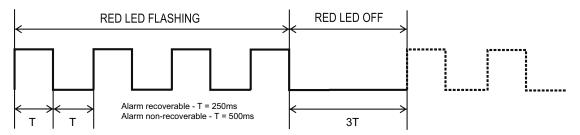


Relay status indication

		Relay contact position	
State	Supply	RSGT /	45mm
State	(green LED)	Alarm (11, 12)	Bypass (21, 24)
Idle	ON	Closed	Open
Ramping	ON	Closed	Open
Bypass	ON	Closed	Closed
Alarm (Auto-recovery)	ON	Open	Open
Alarm (Manual recovery)	ON	Open	Open
Internal fault	ON	Open	Open
Idle (Start to start or stop to start time not elapsed)	Flashing	Closed	Open

Alarms

The RSGT includes a number of diagnostics and protection features each of which is signalled through a flashing sequence on the red LED.





	▼
Number of flashes	2
Alarm	Wrong phase sequence
Alarm description	If the connection to the soft starter is not done in the correct sequence (L1, L2, L3), the RSGT will trigger the wrong phase sequence alarm and the motor will not be started.
Alarm recovery period	N/A
Consecutive alarms for hard reset	1
Action to recover alarm Troubleshooting	User intervention is required to change the wiring sequence to recover alarm. Note: the phase sequence monitoring can be disabled. To disable the alarm, press the Test/Reset button for 10 seconds when the RSGT is in IDLE state. The yellow LED (LED E3) will turn ON. ATTENTION: in this mode, if the wiring is not in the correct sequence, the motor will rotate in the reverse direction. Check that wiring on L1, L2, L3 is in the correct sequence. If you need to reverse the motor, make sure that the phase sequence LED
	is ON (phase sequence protection disabled).
Number of flashes	3
Alarm	Line voltage out of range
Alarm description	At every power-up the RSGT automatically detects the supply voltage level and determines whether it is working on a 220, 400, 480* or 600* V supply. The under- or over- voltage alarm level is then set at a level of -20% and + 20% (from the measured supply voltage level) respectively. If the supply voltage level is out of these limits for more than 5 seconds then the line voltage out of range alarm will be triggered. * Applies to RSGT60 models. Note: for RSGT60 over-voltage alarm level (for the case of a 600V supply) is 675V (600V + 12.5%).
Alarm recovery period	5 minutes (If manual reset mode is applied, alarm can be reset by pressing the Test/Reset button).
Consecutive alarms for hard reset	5
Action to recover alarm	The alarm will self-recover (in auto-recovery mode) after 5 minutes from when the supply voltage is within limits.
Troubleshooting	 Check supply voltage level across L1, L2, L3 terminals. Make sure that you are not using a RSGT40 model on a supply voltage > 440 VAC.
Number of flashes	4
Alarm	Phase loss (motor side)
Alarm description	If any of the phases on the load (motor) side becomes open the RSGT will trip after 5 seconds to protect the motor from running/ starting on 2 phases. Note: this alarm will also be triggered when a current unbalance of > 20% is detected on any of the three line currents for a minimum of 5 secs. Additionally if a SCR and/or bypass relay is open (damaged) the same alarm will be triggered.
Alarm recovery period	5 minutes (If manual reset mode is applied, alarm can be reset by pressing the Test/Reset button).
Consecutive alarms for hard reset	5
Action to recover alarm	Check connections on the output side of the soft starter and on the motor terminals. The alarm will self-recover (in Auto-recovery mode) after 5 minutes.
Troubleshooting	 Check for any loose connections on the T1, T2, T3 side of the soft starter. Check for any loose connections on the motor terminals. Check motor windings.



Number of flashes	5
Alarm	Locked rotor
Alarm description	If a current ≥ 5xFLC setting for 100 msec is detected, the RSGT will issue the locked rotor alarm.
Alarm recovery period	5 minutes (If manual reset mode is applied, alarm can be reset by pressing the Test/Reset button).
Consecutive alarms for hard reset	5
Action to recover alarm	The alarm will self-recover (in Auto-recovery mode) after 5 minutes.
Troubleshooting	 Check that FLC setting is not smaller than motor name plate current. Check that the RSGT model is suitably rated for the motor. Check motor windings resistance to check if motor is damaged.

Number of flashes	6
Alarm	Dry-run
Alarm description	If less than 50% of FLC current flows for 5 seconds, dry-run alarm will be triggered.
Alarm recovery period	5 minutes. (If manual reset mode is applied, alarm can be reset by pressing the Test/Reset button).
Consecutive alarms for hard reset	5
Action to recover alarm	The alarm will self-recover (in Auto-recovery mode) after 5 minutes
Troubleshooting	 Check that the FLC setting is not too much higher than the motor name plate current. Check motor load.

Number of flashes	7
Alarm	Over-temperature
Alarm description	The RSGT constantly measures the heatsink and thyristors (SCRs) temperature. If the maximum internal temperature is exceeded (for 0.5 sec) an overtemperature alarm is triggered. This condition can be triggered by too many starts per hour, an over-load condition during starting and/or stopping or a high surrounding temperature.
Alarm recovery period	Depends on the cooling period. (If MANUAL reset mode is applied, alarm can be reset by pressing the Test/Reset button). The RSGT will only recover if the internal temperature is within safe limits.
Consecutive alarms for hard reset	5
Action to recover alarm	The alarm will self-recover (in Auto-recovery mode) - the recovery period will depend on the cooling time required by RSGT. The higher the surrounding temperature, the longer the cooling period.
Troubleshooting	 Check that the specified number of starts/hr are not exceeded. Check that the surrounding temperature around the soft starter is within limits.



Number of flashes	8
Alarm	Overload
Alarm description	The overload alarm can be triggered in case of the following conditions: Measured current > 1.05 x FLC during transition from ramp-up to bypass and also during bypass. Load current > FLC. Trip time will vary according to Trip Class 10.
Alarm recovery period	Depends on the cooling period. (If manual reset mode is applied, alarm can be reset by pressing the Test/Reset button). The RSGT will only recover if the internal temperature is within safe limits.
Consecutive alarms for hard reset	5
Action to recover alarm	The alarm will recover automatically after (approx.) 5 minutes. If manual reset mode is enabled, press Test/Reset button. Note: allow enough time for the motor to cool before attempting the next start.
Troubleshooting	 Make sure that the FLC setting is according to the current on the motor name plate. Check for any blockages in the load. If overload alarm occurs during ramp-up try to set a shorter ramp-up time or increase the FLC setting.

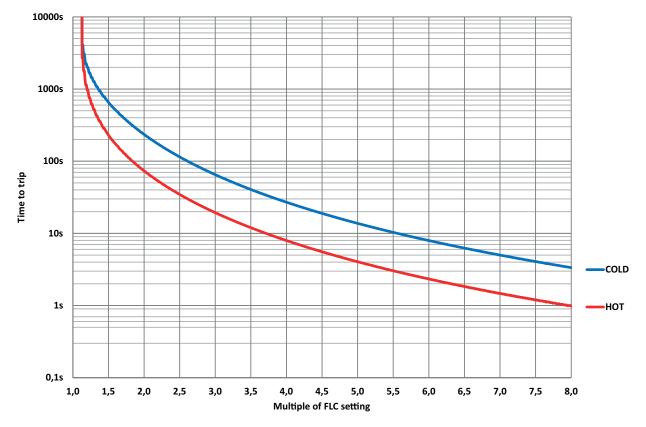


Fig. 8 RSGT Class 10 motor overload trip profile



Number of flashes	9
Alarm	Supply voltage unbalance
Alarm description	The RSGT measures the voltages on all three phases and if there is a difference of more than 20 % for ≥ 5 sec between any of the phases, the RSGT will trigger the voltage unbalance alarm
Alarm recovery period	5 minutes
Consecutive alarms for hard reset	5
Action to recover alarm	The alarm will recover automatically after 5 minutes. If manual reset mode is enabled, press Test/Reset button.
Troubleshooting	 Check supply voltage level across L1, L2, L3 terminals. Check connections on the L1, L2, L3 terminals.

Number of flashes	10
Alarm	Shorted thyristor (SCR)
Alarm description	In case the RSGT detects that there is a damaged (shorted) thyristor (SCR) on any of the three phases, the soft starter will trip.
Alarm recovery period	N/A
Consecutive alarms for hard reset	1
Action to recover alarm	Note: this alarm is not resettable and it is suggested to replace the unit and contact a Carlo Gavazzi representative should this alarm occur.
Troubleshooting	 Check resistance across L1-T1, L2 - T2 and L3-T3 to check for any short. If any of the SCRs is damaged, replace the soft starter.

Number of flashes	Fully ON
Alarm	Internal fault
Alarm description	In case there is an internal fault in the RSGT circuitry, the Red LED will remain continuously ON.
Alarm recovery period	N/A
Consecutive alarms for hard reset	1
Action to recover alarm	Note: this alarm is not resettable and it is suggested to replace the unit and contact a Carlo Gavazzi representative should this alarm occur.
Troubleshooting	Turn ON and OFF the device. If alarm still persists replace the soft starter.



Short circuit protection

Type "1" co-ordination requires that, under short-circuit conditions, the contactors or starter shall cause no danger to persons or installation and may not be suitable for further service without repair and replacement of parts. The product variants listed in the table hereunder are suitable for use on a circuit capable of delivering not more than 5,000 symmetrical Amperes, 400 or 600 Volts maximum when protected by fuses. Tests at 5,000 A were performed with Class RK5 fuses, fast acting; please refer to the table below for maximum allowed ampere rating of the fuse. Use fuses only.

Note: For fuse size of 600A or less, Class CC, G, H, K, J, RK1 or T fuses can be used instead of RK5 fuses.



Time delay fuses

Item No.	Max. fuse size [A]	Current [kA]	Class	Max. voltage [VAC]
RSGT12	15			
RSGT16	20	5	RK5	600
RSGT25	25			



Manual motor starters

Item No.	Model No.	Current [kA]	Max. voltage [VAC]
RSGT12	GMS32H-17		
RSGT16	GMS32H-17	10	400
RSGT25	GMS32H-32		

Note: products protected with manual motor starters must be wired with a minimum length of 2.0 m (10.0 m for 12, 16 A models) of Cu wire conductor with a maximum cross-sectional area of 2.5 mm² for 12 Arms and 16 Arms devices, 10 mm² for 25 Arms devices. The length includes the conductors from the voltage source to the manual motor starter to the soft starter and from the soft starter to the load.



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