# Dupline® Car Park System Type GP 6565 0201 Direction Indicator with red and green LED





- · Quick indication of free parking bays
- Low power consumption
- Brightly lit LED indicator
- Configurable device for monitoring free parking bays in an area
- · Protected against dust and moisture
- Dupline® 3-wire system with power
- Address coding with GAP1605

#### **Product Description**

The GP6565 0201 direction indicator forms part of the Car Park system which contains several variants of sensors and passive LED modules. Furthermore, the car park system contains displays for displaying the number of free parking bays.

The direction indicator is installed over the roadway and points out the correct route to the driver using brightly lit green LED arrows. Direction indicators with red

crosses indicate areas that are either pre-booked or occupied.

It is possible to install up to 36 direction indicators in one carpark system.

The direction indicator is the intelligent part of the car park system, and using different settings, it is possible to create different functions, depending on the user's requirements and the size of the facility.

Ordering Key	_ GP 0303 UZ	GP 0303 U2U I		
Type: Dupline® ————————————————————————————————————				

#### **Type Selection**

Inputs

Mains

Irdarina Kay

GP 6565 0201 Direction indicator, red/green

# **Input/Output Specifications**

2-pin connector for Bus L<sub>1</sub>

- Pin 1: Dupline® (L<sub>1</sub> bus)
- Pin 2: Dupline® + (L<sub>1</sub> bus)

3-pin connector for Bus L<sub>2</sub>

- Pin 1: Dupline® + (L<sub>2</sub> bus)
- Pin 2: GND Minus supply or Dupline® minus (L<sub>2</sub> bus)
- Pin 3: 24 VDC external power supply (L2 bus)

RJ45 connector for address programming using GAP 1605

3-pin connector for RS485

- Pin 1: A (RS485)
- Pin 2: Dupline® or GND (L2 bus)
- Pin 3: B (RS485)

# **Supply Specifications**

Power supply:

Current consumption from L<sub>1</sub> bus:

Current consumption from  $L_2$  bus:

Current consumption from external power supply:

Power consumption:

Electrical insulation between Dupline® bus L<sub>1</sub> and L<sub>2</sub>:

24 V DC min.; 30 VDC max. (Overvoltage category III (IEC60664))

< 1 mA

< 1 mA

212 mA

< 5 W

1,500 Vrms



#### **General Specifications**

-	
<b>LED indication:</b> Occupied: Space available:	Red cross lit constantly Green arrow lit constantly
The direction indicator uses four Dupline® channels and can be programmed as follows:  • I/O 1: Start marker	Input
■ I/O 2: End marker	Input
I/O 5: Start marker	Output
<ul><li>I/O 6: End marker</li></ul>	Output
<ul> <li>I/O's 1 and 5 are start mar- kers which is the Dupline®address before the first sensor</li> </ul>	
<ul> <li>I/O's 2 and 6 are end mar- kers which is the Dupline®address after the last sensor</li> </ul>	

#### Connector for RS485:

- Follows the interface standard for EIA-RS485
- Data speed is 4,800 bps
- Flux of the data
- Asynchronous mode, continuous receiving with no answer
- Frame composition: 3 x (1 start bit + 8 data bit + 1 stop bit)

#### Note

The starting of the frame is synchronized with the last positive edge of the Dupline® frame with a delay of 1 mSec

#### **Environment**

- Protection: IP 66
- Operating temperature: -25 °C to 70°C (-13°F to 158°F)
- Storage temperature: -40°C to 85°C (-40°F to 185°F)
- Pollution degree: 3 (IEC 60664)
- Relative humidity: Maximum 93%
- Dimensions: 110 x 110 x 66 mm
- Material: The housing is made of polypropylene. The direction indicator lid is made of clear Polycarbonate

# **Mode of Operation**

The GP6565 0201 direction indicator is the intelligent part of the car park system. Its primary purpose is to read the number of free parking bays. Its secondary function is to transmit this information, e.g. to displays GP6763 010X. The direction indicator also uses the information gathered to guide the cars around in the parking area using a green arrow or a red cross, respectively. The unit consists, among other things, of two galvanically separated Dupline® busses  $L_1$  and  $L_2. The two buses are programmed using GAP 1605 or locally using rotary switches and switches. The programming and connection of the two busses depends on the mode for which the system is set. The four different modes and the programming will be explained later.$ 

Depending on the mode selected, either display GP6763 010X or an intelligent unit can be connected to the connector for RS485. The GP6763 010X is a passive unit that can indicate the number of free parking bays or be used as a monitor when programming the GP6565 0201.

All Dupline® addresses can be used, except the address used for multiple calibration and the synchronization addresses. Normally, the addresses used for this purpose are

- calibration address: A1 (but optional)
- synchronization address: P5 and P6
- non-operational addresses: P7 and P8

The synchronization addresses are explained in the datasheet for GP34960005. P7 and P8 have no function and must not be used.

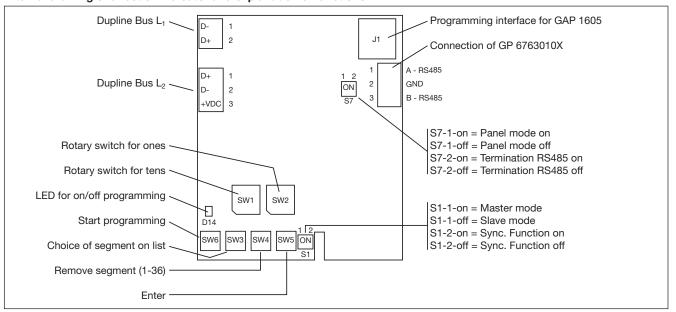
Example of GAP programming:

I/O 1 and 5 = A2 marker start

I/O 2 and 6 = N2 marker end

This means that there are 103 sensors in this system.

#### Internal drawing of direction indicator and explanation of functions





# **Programming Modes**

The direction indicator can be set for different modes according to requirements. Remember to set the DIP switches before the power supply is turned on. The different modes are

The different modes are designated as follows:

- Sync. operating mode
- · Master operating mode
- Slave mode
- Panel mode

# Sync. Operating Mode (Synchronization)

This mode is configured by setting DIP switch S1-2 (on). Sync. mode can only be allocated to one GP6565 0201 in every system. The GP6565 0201 set to sync. mode can be set to either master mode or slave mode concurrently.

Sync. mode operates only on  $L_2$ . This means that, if several directions indicators are connected via  $L_2$ , only one must be set into sync. mode.

#### **Master Operating Mode**

This mode is configured by setting DIP switch S1-1 (on). Master mode is also a summary mode where all available parking bays (from the sensors) are collected from  $L_2$ .  $L_1$  is not used in this mode. If anything is connected to  $L_1$  in master mode, this data will thus be ignored.

Only one direction indicator in this network can be set to sync. mode. It is possible to connect several direction indicators to the system without sync., in order to see the total or individual number of free spaces, regardless of position on the bus.

The direction indicator will indicate a green LED if there are available spaces, whereas it will indicate a red cross if no spaces are free. This data will be transferred simultaneously to display GP6763 010X through a RS485 interface.

#### **Programming Procedure**

The direction indicator must be taught the areas to be controlled. This is done via the internal programming inside the direction indicator. The internal programming takes place using switches and rotary switches on the direction indicator PCB and has nothing to do with Dupline® addresses and

Dupline® programming.

Press SW6 for approx. 1 sec. to activate the programming mode. LED D14 will turn off briefly.

If nothing is pressed for 15 sec., the programming mode will exit

Deleting the memory in GP6565 0201:

Set SW1 and SW2 respectively to 99. Press SW5 for approx. 1 sec. LED D14 will confirm deletion of the memory by turning off briefly for approx. 2 seconds.

Programming of segments (1-36) is set on SW1 and SW2, respectively, and confirmed by pressing SW3 (enter). This is confirmed by LED D14 which will turn off briefly for approx. 1 second. If you want to enter more segments, repeat the above procedure.

It is also possible to delete segments. Set SW1 and SW2 to the desired segment and press SW4 for approx. 1 second. LED D14 will confirm this by turning off briefly for 1 second. By setting SW1 and SW2 to 00, it is possible, by pressing SW5, to scroll through the program. Read the settings directly on display GP6763 010X.

ACTION	SWSW2 setting	Button to be pressed	LED	Indication on GP6763010x
Entering into procedure		SW6	OFF ?ON	P 00
Clear all the memory	99	SW5	OFF x 2"	C00
Segment number to be inserted	No. of segment	SW3	OFF x 1"	A00
Segment number to be removed	No. of segment	SW4	OFF x 1"	R00
See complete list of programmed area	00	Sw5	OFF x 2"	L00



#### **Slave Operating Mode**

This mode is configured by setting DIP switch S1-1 (off). This is a "stand alone" mode without external control (PC, PLC or similar). Slave mode uses both Dupline® buses  $L_1$  and  $L_2$ . In slave mode, the direction indicator will take the number of free parking bays from  $L_1$  and put them into a segment on  $L_2$ . The direction indicator will indicate a green LED if there are available spaces, whereas it will indicate a red cross if no spaces are free. This data will be transferred simultaneously to display GP6763 010X through a RS485 interface.

There will be no need for  $L_2$  if there is no connection between the direction indicators. The direction indicators can detect this automatically.

If  $L_1$  is disconnected by accident, the direction indicator LED will show a red cross.

The  $L_2$  Bus is reserved only to connect all the indicators distributed along the park building, as it supports a special data protocol. On this Bus the indicators working in SLAVE mode insert binary data, which hold information about vacant parking places available in a determined area. This function is supported by a dedicated protocol derived from the standard one; this protocol uses 4 consecutive frames of the original Dupline® protocol.

A coding status for allocating up to 36 indicators should be provided by one of the indicators previously configured in SYNC operating mode. This coding status divides each frame into 9 data fields 14 bit wide with 6 bit for the indicator address and 8 bit for the indication of a vacant parking place.

#### Address mapping of the indicators in the L2 Dupline® frame

L<sub>2</sub> assignment with indicator configured in MASTER or SLAVE mode

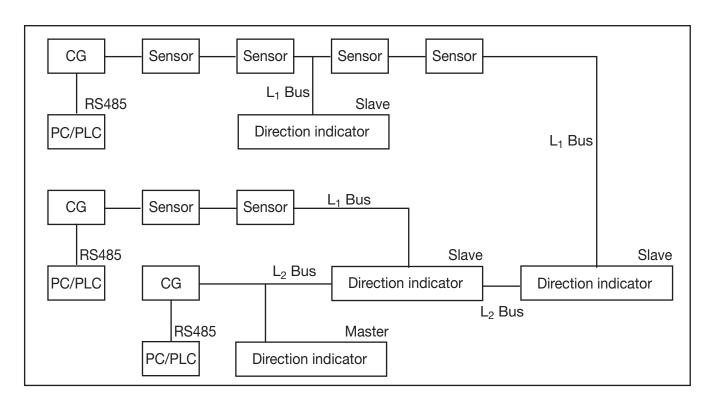
1st frame	Address assignment	Data assignment
Direction indicator N.36	A1 - A6	A7 - B6
Direction indicator N.35	B7 - C4	C5 - D4
-	-	-
Direction indicator N.29	M3 - M8	N1 - N8
Direction indicator N.28	O1 - O6	O7 - P6

2nd frame	Address assignment	Data assignment
Direction indicator N.27	A1 - A6	A7 - B6
Direction indicator N.26	B7 - C4	C5 - D4
-	-	-
Direction indicator N.20	M3 - M8	N1 - N8
Direction indicator N.19	01 - 06	O7 - P6

3rd frame	Address assignment	Data assignment
Direction indicator N.18	A1 - A6	A7 - B6
Direction indicator N.17	B7 - C4	C5 - D4
-	-	-
Direction indicator N.11	M3 - M8	N1 - N8
Direction indicator N.10	01 - 06	07 - P6

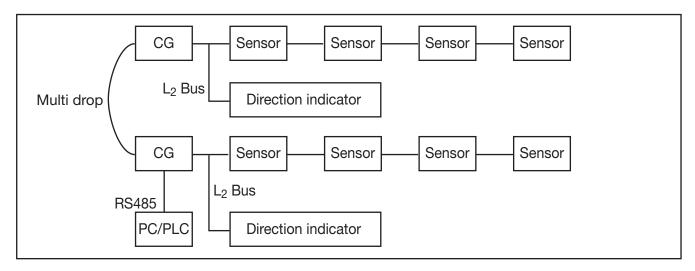
4th frame	Address assignment	Data assignment
Direction indicator N.9	A1 - A6	A7 - B6
Direction indicator N.8	B7 - C4	C5 - D4
-	-	-
Direction indicator N.2	M3 - M8	N1 - N8
Direction indicator N.1	O1 - O6	O7 - P6





#### **Panel Operating Mode**

This mode is configured by setting DIP switch S7-1 (on). remote control (PC, PLC etc.). Only one bus L2 is used. L1 This is the lowest mode and is used if there is a need for must not be connected to the direction indicator.



L<sub>2</sub> assignment with indicator configured in PANEL mode

Configuration	SLAVE on L₁	SLAVE on L <sub>2</sub>	MASTER on L <sub>2</sub>	Panel on L <sub>2</sub>
Address occupancy	2 (for markers)	6 (bit for address) + 8 (for data)	6 (bit for address) + 8 (for data)	8 (for data)



# **Channel Mapping of the Sensors**

#### Address mapping of the sensors in the L<sub>1</sub> Dupline® frame

L<sub>1</sub> assignment with all sensors configured at full capacity (4 I/O configuration)

Dupline assignment	I/O 1	I/O 5	I/O 6	I/O 7
Sensor N.1	A2	A3	P5	A1
Sensor N.2	A4	A5	P6	A1
-	-	-	-	-
Sensor N.60	P1	P2	P5	A1
Sensor N.61	P3	P4	P6	A1

L<sub>1</sub> assignment with all sensors configured at reduced capacity (2 I/O configuration)

Dupline assignment	I/O 1	I/O 6	1/0 7	
Sensor N.1	A2	P5	A1	
Sensor N.2	A3	P6	A1	
-	-	-	-	
Sensor N.122	P3	P5	A1	
Sensor N.123	P4	P6	A1	

 $L_{\scriptscriptstyle 1}$  assignment with sensors at reduced capacity and one Direction indicator

Dupline assignment	Sensor I/O 1	Sensor I/O 7	I/O 6	Indicator Start marker	Indicator End marker
Sensor N.1	A3	A1	P5		
Sensor N.2	A4	A1	P6		
-	-	-	-		
Sensor N.120	P2	A1	P5		
Sensor N.121	P3	A1	P6		
Direction indicator				A2	P4

<sup>\*</sup>NOTE: P5, P6, P7 and P8 address must not be assigned to the End marker of indicator. P5 and P6 are assigned to the sensors' sync. signal. P7 and P8 must not be used.

#### Address mapping of the sensors in the L2 Dupline® frame

L<sub>2</sub> assignment with indicator configured in PANEL mode

Dupline frame	Data assignmment		
Direction indicator N.1	A1 - A8		
Direction indicator N.2	B1 - B8		
-	-		
Direction indicator N.15	O1 - O8		
Direction indicator N.16	P1 -P8		



# Example of a System in Slave Mode with tree Sensors, two Direction Indicators and two Displays

The direction indicator is set up as a "slave" using switches. It is programmed using GAP 1605.

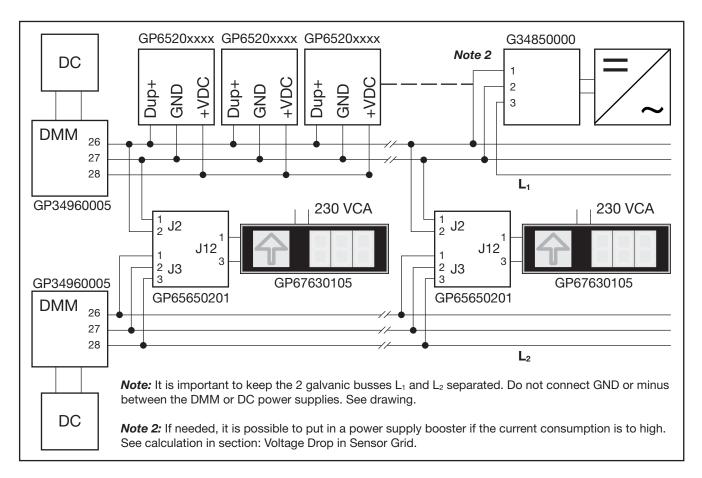
I/O's 1 and 5 are programmed to "A2" (marker start).

I/O's 2 and 6 are programmed to "A6" (marker end).

The I/O 1 on the sensors are addressed "A3", "A4" and "A5", respectively, also using GAP 1605. The I/O6 on the sensors is addressed P5, P6 and P5 respectively. The I/O 7

is addressed to A1. The direction indicator now automatically knows which sensors to detect, because it looks at all addresses between start and end marker. This means that there can be many direction indicators on the same Dupline® network.

The display also have a function as a monitor when programming the direction indicator. (See Fig. 4)



# **Voltage Drop in Sensor Grid**

Due to the high current consumption of each sensor module, precautions should be taken to avoid voltage drops in the sensor network.

As indicated, the car park system is a 3-wire system.

Different power supply types can be used to supply the sensors, including third-party power supplies. Dupline® provides two different power supply couplers: G3485 0000, which is a power supply coupler, or DMM G3496 xxxx, which also includes an integrated channel generator.

They both feature a pulsating 30 VDC/3 A output on the third wire.

The DC supply for G3485 0000 is capable of supplying twice the total load current, as the output voltage on G3485 0000 is pulsating.

When using G3485 0000, the following should be considered:

The voltage drop for the output on G3485 0000 is  $\leq$  1.0 V. That is, for a 30 VDC input on the module you can achieve a maximum output of 29 VDC. Together with the voltage drop for the output of the GP65xx xxxx sensor, this must be taken into consideration when selecting the output voltage for the DC supply.

The voltage drop on the GP65xx xxxx sensors is calculated as: Uout G3485 0000 – Uin GP65xx xxxx = 29-22 = 7 V

There is a limit for the voltage drop Vcw in the longest common wire. This limit can be calculated as follows:

Vcw = Rcw x lcw

Vcw = Voltage drop in longest common wire lcw = Total current in longest common wire Rcw = Resistance in longest common wire



If the load is distributed evenly along the 3-wire, Vcw = 3.5 V max.

Vcw = (Vout (G3485 0000)-Vin (G6520 220x))/2 = (29-22)/2 = 3.5 V

In order to avoid voltage drops in the system, further G3485 0000 supply units can be added along the wire.

#### Note:

Remember to install the DC supply and the G3485 0000 supply unit close to each other to avoid voltage drops between the two modules. See the wiring diagram on the following page.

# Calculation example for maximum wire length, sensor side:

Network with 30 sensors:

- G3485 0000 power supply output voltage = 29 VDC
- 30 GP6520 2201 sensors with 37 mA current consumption
- Cable = 1.5 mm<sup>2</sup>. Cable resistance = 13  $\Omega$ /km
- Total current consumption = 30 x 37 = 1110 mA

**Note:** Please note that the calculation of the direction indicator's current consumption is made on the  $L_2$  bus and not on the  $L_1$  bus. Therefore, the indicator is not included in the total current consumption of this calculation.

At a voltage drop for G3485 0000 of 3.5 V, the internal resistance is:

 $R = 3.5 \text{ V} / 1110 \text{ mA} = 3.15 \Omega$ 

Maximum wire length = 3.15  $\Omega/13 \Omega/km$  = **242 meters** 

# Calculation example for maximum number of sensors at a specific wire length:

- Wire length stated at 500 m = (0.5 km)
- Cable type = 1.5 mm2. Cable resistance = 13  $\Omega$ /km
- Max. voltage drop = 3.5 VDC
- Max. current consumption for sensor = 37 mA

Total wire resistance = 0.5 km x 13/km = 6.5  $\Omega$ 

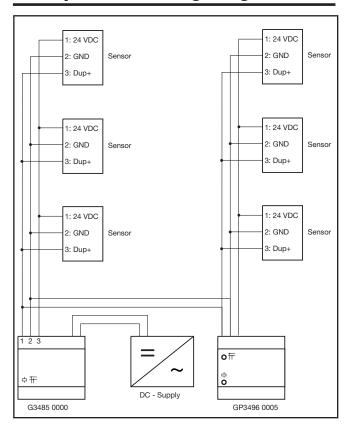
Max. current consumption = 3.5 / 6.5 = 538 mA

Maximum number of sensors in the network: 538 / 37 = 14 sensors

#### Rule-of-thumb:

For each 100 meters, 60 sensors can be placed when using a  $1.5 \ \text{mm}^2$  cable.

# **Example of a Wiring Diagram**



#### **Dimensions**

