# **Output Modules for Rollerblind Motors**



# **BH4-RO5ADC2-230**

Up/down control of 2 rollerblind motors

**H4-housing** 

For mounting on DIN-rail (EN 50022)

LED-indications for supply smart-house carrier and motor up/down

AC power supply

Channel coding by BGP-COD-BAT



#### **OUTPUT SPECIFICATIONS**

2 SPST x 2 DPDT relays **Outputs** 

Resistive loads Mechanical lifetime Electrical lifetime

DC 13

5 A/24 VDC

 $\geq 1 \times 10^6$  operations

(at max load)

 $\geq 1 \times 10^5$  operations

Operating frequency Insulation voltage

≤ 7200 operations/h

≥ 4 kVAC (rms) Outputs - smart-house

Response time 1 pulse train

	GENERAL SPECIFICATIONS	
Output OFF delay Upon loss of smart-house carrier	20 ms	Pollution degree Operating temp Storage tempera
Power ON delay Power OFF delay	Typ. 2 s ≤ 1 s	Humidity (non-co
Indication for Supply ON Output ON	LED, green 4 LEDs, red	Mechanical resis Shock Vibration
smart-house carrier  Environment	(one per motor or direction) LED, yellow	Dimensions Material (see Technical in

3 (IEC 60664)
$-20^{\circ}$ to $+50^{\circ}$ C (-4° to $+122^{\circ}$ F)
-50° to +85°C (-58° to +185°F)
20 to 80%
15 G (11 ms)
2 G (6 to 55 Hz)
H4-housing
300 g

### SUPPLY SPECIFICATIONS

IP 20 B

Power supply AC types Installations cat. III (IEC 60664) Rated operational voltage

through term. 21 & 22

Degree of protection

230 VAC ± 10% (IEC 60038)

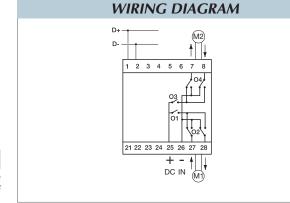
Frequency 45 to 65 Hz Drop-out tolerance ≤ 40 ms Power consumption Typ. 3.8 VA Power dissipation ≤ 9 W Transient protection volt. 230 4 kV

Insulation voltage

Supply - smart-house ≥ 4 kVAC (rms) ≥ 4 kVAC (rms) Supply - Outputs smart-house - Outputs ≥ 4 kVAC (rms)

## **TYPE SELECTION**

Supply Ordering no. 230 VAC BH4-RO5ADC2-230



# **DIMENSIONS** (mm) 21 22 23 24 25 26 27 28 (8) (8) (8) (8) (8) (8) (8)

### **MODE OF OPERATION**

As indicated on the wiring diagram, there are two relays in series to control each motor. O1 is used to switch Motor 1 ON/OFF and O2 is used to control the direction of The smart-house controller pro-Motor 1 UP/DOWN. Correspondingly O3 (ON/OFF) and O4 (UP/DOWN) are used to control Motor 2. O1, O2, O3 and O4 may be coded individually by means of the code programmer BGP-COD-

BAT. The default setting of the module is to switch all outputs off in case of loss of smart-house carrier signal.

vides intelligent functions that makes it easy for the user to control the rollerblind motors individually or several at the same time (all UP or all DOWN).

## **ACCESSORIES**

DIN-rail FMD 411